

**AMENDMENTS TO THE SPECIFICATION:**

Please replace paragraph [0001] with the following amended paragraph:

The invention relates to an apparatus and a method for automating treadmill therapy for rehabilitating walking-disabled patients ~~according to Claim 1 or 13~~ respectively.

Please replace paragraph [0008] with the following amended paragraph:

According to the invention, this objective is realized with a driven orthotic device ~~according to the wording in Claim 1 and~~ and an associated method for operating the orthotic device ~~according to the wording of Claim 13~~ as described herein.

Please replace paragraph [0022] with the following amended paragraph.

Fig. 1 shows a schematic portrayal of the principle of the treadmill training system with driven orthotic device, in a variation with a parallelogram for stabilizing the patient. At each treadmill 1, one each rail 3 of a railing on supports 2 is mounted on each side of the walking surface, ~~said~~ the rail being adjustable in height with a mechanism as is the case with a set of parallel hand rails. At the rear end of the rail 3, a parallelogram 5 that will be described in more detail later has been attached in a movable manner. The parallelogram 5 is used for stabilizing an orthotic device 6 that is designed to receive the patient and is located above the treadmill 1. The parallelogram 5 permits a movement of the orthotic device 6 only on a predetermined sector, whereby the movement is indicated by an arrow. This stabilizes both the orthotic device and the patient so that he is unable to tip either

laterally, forward or backward. The patient' s upper body is connected via a hip belt 7 and a chest belt 8 with the orthotic device 6 and is held in this way in a constant vertical position. The height adjustability of the rail 3 also makes it possible to adjust the height of the parallelogram 5. The parallelogram 5 also is automatically adjusted in height for patients of different heights when the rail 3 is adjusted.